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UTILITY PATENT APPLICATION TRANSMITTAL

(Only for new nonprovisional applications under 37 CFR 1.53(b))

Attorney Docket No. 35.C14184

First Named Inventor or Application Identifier

MASAHICO KIKUZAWA

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APPLICATION ELEMENTS

See MPEP chapter 600 concerning utility patent application contents.

ADDRESS TO:Assistant Commissioner for Patents
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1. Fee Transmittal Form
(Submit an original, and a duplicate for fee processing)
2. Specification Total Pages **28**
3. Drawing(s) (35 USC 113) Total Sheets **10**
4. Oath or Declaration Total Pages **1**
- a. Newly executed (original or copy)
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c. Copy from a prior application (37 CFR 1.63(d))
(for continuation/divisional with Box 17 completed)
[Note Box 5 below]
- i. **DELETION OF INVENTOR(S)**
Signed Statement attached deleting
inventor(s) named in the prior application, see
37 CFR 1.63(d)(2) and 1.33(b).
5. Incorporation By Reference (useable if Box 4c is checked)
The entire disclosure of the prior application, from which a copy of
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6. Microfiche Computer Program (Appendix)
7. Nucleotide and/or Amino Acid Sequence Submission
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- a. Computer Readable Copy
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ACCOMPANYING APPLICATION PARTS

8. Assignment Papers (cover sheet & document(s))
9. 37 CFR 3.73(b) Statement
(when there is an assignee) Power of Attorney
10. English Translation Document (if applicable)
11. Information Disclosure Statement (IDS)/PTO-1449 Copies of IDS Citations
12. Preliminary Amendment
13. Return Receipt Postcard (MPEP 503)
(Should be specifically itemized)
14. Small Entity Statement filed in prior application
Statement(s) Status still proper and desired
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17. If a CONTINUING APPLICATION, check appropriate box and supply the requisite information:
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	TOTAL CLAIMS (37 CFR 1.16(c))	17-20 =	0	X \$ 18.00 =	\$ 0.00
	INDEPENDENT CLAIMS (37 cfr 1.16(b))	3-3 =	0	X \$ 78.00 =	\$ 0.00
	MULTIPLE DEPENDENT CLAIMS (if applicable) (37 CFR 1.16(d))			\$ 260.00 =	\$ 0.00
				BASIC FEE (37 CFR 1.16(a))	\$ 690.00
				Total of above Calculations =	\$ 690.00
	Reduction by 50% for filing by small entity (Note 37 CFR 1.9, 1.27, 1.28).				
				TOTAL =	\$ 690.00

19. Small entity status

- a. A Small entity statement is enclosed
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- c. Is no longer claimed.

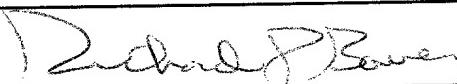
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SIGNATURE OF APPLICANT, ATTORNEY, OR AGENT REQUIRED

NAME	Richard P. Bauer - Reg. No. 31,588
SIGNATURE	
DATE	January 20, 2000

RPB\jab

IMAGE SENSING APPARATUS

BACKGROUND OF THE INVENTION

Field of the Invention

The present invention relates to an image sensing apparatus having a noise reduction circuit and to a control method for such an image sensing apparatus. The invention also relates to a storage medium storing a program for sensing an image of an object, which program is executed by a CPU of the image sensing apparatus.

Related Background Art

A conventional video camera has a noise reduction circuit for removing noises from a video signal. Noise reduction circuits as well as various other video signal processing circuits are now made of digital components along with the advent of digital video (DV) cassettes (SD format) and the like.

A cyclic type using a field memory is generally used for a digital noise reduction circuit. As the price of a memory lowers nowadays, the digital noise reduction circuit is used also for general video cameras of home use.

A cyclic type noise reduction circuit will be described which removes noises by using field images having correlation in time. As shown in Fig. 3, a cyclic noise reduction circuit has an input terminal

51, an adder 52, a subtractor 53, a multiplier 54, a field memory 55, a limiter 56 and an output terminal 57.

5 A signal S_i input from the input terminal 51 is supplied to the adder 52 and subtractor 53. The subtractor 53 subtracts the signal S_i from a signal S_f delayed by the field memory 55 to thereby detect a noise signal S_{n1} between fields. The detected signal S_{n1} is supplied to the limiter 56.

10 Motion components contained in the signal S_{n1} are eliminated by the limiter 56 which outputs a signal S_{n2} . This signal S_{n2} is multiplied by an externally supplied coefficient K (hereinafter called a cyclic coefficient) by the multiplier. This signal $K \cdot S_{n2}$ is 15 supplied to the adder 52.

The adder 52 adds the signal S_i to the signal $K \cdot S_{n2}$ to remove noise components from the signal S_i . A signal S_o output from the adder 52 is supplied to the field memory 55 and also output from the output terminal 57.

20 For the simplification of description, it is assumed that $S_{n1} = S_{n2} = S_n$. The signal S_n is therefore given by the following equation (1):

$$S_n = S_f - S_i \quad \dots (1)$$

25 The signal S_o is given by the following equation (2):

$$S_o = S_i + K \cdot S_n$$

$$\begin{aligned} &= S_i + K \cdot (S_f - S_i) \\ &= (1 - K) \cdot S_i + K \cdot S_f \quad \dots (2) \end{aligned}$$

As seen from the equation (2), the signal S_o having less noise components can be obtained as in the following. Since the signal S_i contains noise
5 components and the signal S_f is a delayed signal of the signal S_o from which noise components are eliminated, the noise components become smaller the more the cyclic coefficient K is made as near as the value 1. If the
10 cyclic coefficient K is set to 0, the signal S_i itself becomes the signal S_o .

The more effectively the noise components can be removed the more the cyclic coefficient K is made as near as the value 1. A video signal generated by a
15 video camera is more likely to be affected by noises, because of high density mount of small components, high speed digitalization, high speed signal processing, and high speed component control. In order to avoid this,
20 it is required to set the amount of noise reduction larger.

However, if the amount of noise reduction made larger, although the noise reduction effect is improved, influence of a preceding field upon a current field becomes large. Therefore, a latent image of a
25 scene having a moving object becomes conspicuous.

This problem also occurs when a zoom operation is performed because the size of an object changes even if

the object does not move.

SUMMARY OF THE INVENTION

It is an object of the invention to provide an
5 image sensing apparatus capable of sensing an image of
an object always in good conditions by realizing an
optimum noise reduction process even under various
photographing conditions and even with various
functions of the apparatus, a control method for the
10 apparatus, and a storage medium storing a program for
realizing such a function.

In order to achieve the above object of the
invention, according to one aspect of the invention,
there is provided an image sensing apparatus which
15 comprises: noise reduction means for reducing noises of
a sensed image by utilizing images having correlation
in time; zoom control means for controlling a zoom
magnification factor of the image sensing apparatus;
judging means for judging whether the zoom control
20 means is executing a zoom operation; and setting means
for setting a control value for the noise reduction
means in accordance with a judgement result by the
judging means.

According to another aspect of the invention,
25 there is provided an image sensing method which
comprises the steps of: reducing noises of a sensed
image by utilizing images having correlation in time;

controlling a zoom magnification factor of the image sensing apparatus; judging whether the zoom control step is executing a zoom operation; and setting a control value for the noise reduction step in accordance with a judgement result at the judging step.

5

According to another aspect of the invention, there is provided a storage medium storing a program for executing an image sensing method which comprises the steps of: reducing noises of a sensed image by utilizing images having correlation in time;

10

controlling a zoom magnification factor of the image sensing apparatus; judging whether the zoom control step is executing a zoom operation; and setting a control value for the noise reduction step in accordance with a judgement result at the judging step.

15

Other objects and advantages of the present invention will become apparent from the following detailed description when read in conjunction with the accompanying drawings.

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BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram showing the structure of an image sensing apparatus according to an embodiment.

25

Fig. 2 is a block diagram showing the structure of a system control unit.

Fig. 3 is a block diagram showing the structure of a cyclic type noise reduction circuit.

Fig. 4 is a flow chart illustrating the sequence
of a noise reduction control process.

Fig. 5 is a flow chart illustrating the sequence
of a noise reduction control process to be followed by
the flow chart shown in Fig. 4.

Fig. 6 is a graph showing the relation between the
brightness of an object and the value of a cyclic
coefficient K in a zoom stop mode and in a zoom
operation mode.

Fig. 7 is a graph showing the relation between the
brightness of an object and the value of a cyclic
coefficient K in the zoom stop mode and zoom operation
mode, and at Steps 1 and 2.

Fig. 8 is a memory map of a ROM as a storage
medium.

Fig. 9 is a block diagram showing the structure of
an image sensing apparatus according to another
embodiment.

Fig. 10 is a flow chart illustrating the sequence
of a noise reduction control process.

Fig. 11 is a flow chart illustrating the sequence
of a noise reduction control process to be followed by
the flow chart shown in Fig. 10.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Preferred embodiments of an image sensing
apparatus, a control method therefor and a storage

medium according to the invention will be described.

Fig. 1 is a block diagram showing the structure of an image sensing apparatus. In Fig. 1, reference numeral 11 represents a zoom lens for focussing the image of an object, reference numeral 12 represents a diaphragm for adjusting a light quantity, reference numeral 13 represents an image pickup device made of a CCD for converting input light into an electric signal, and reference numeral 14 represents a sample/hold AGC circuit for sample/hold and gain adjustment.

Reference numeral 15 represents an analog-digital (A/D) converter unit for A/D conversion, and reference numeral 16 represents a video signal processing unit for processing a signal and generating a video signal. Reference numeral 17 represents an electronic zoom unit having a field memory for image cut and paste, magnification, and interpolation. Reference numeral 18 represents a noise reduction (NR) unit having a field memory for reducing noises from a video signal. Reference numeral 19 represents a lens position detection unit for detecting the position of the zoom lens, and reference numeral 20 represents a lens drive unit for driving the zoom lens.

Reference numeral 21 represents a system control unit for controlling the entirety of the image sensing apparatus. Fig. 2 is a block diagram showing the structure of the system control unit 21. The system

control unit 21 has a CPU 31, a ROM 32, a RAM 33 and an I/O interface which are well known in the art. ROM 32 stores programs and table values to be described later, the programs being executed by CPU 31.

- 5 Reference numeral 22 represents a zoom operation key unit having keys for zoom operations. Reference numeral 23 represents a wide key for moving the zoom lens in a wide (wide = image reduction) direction, and reference numeral 24 represents a telephoto key for
10 moving the zoom lens in a telephoto (telephoto = image magnification) direction. For example, the wide key 23 and telephoto key 24 are keys of a see-saw type moving together. Each key outputs a signal representative of a depression pressure to the system control unit 21.
15 The noise reduction (NR) unit 18 is made of a conventional cyclic type noise reduction circuit. Fig. 3 shows the structure of a cyclic type noise reduction circuit. The noise reduction circuit has the input terminal 51, adder 52, subtractor 53, multiplier 54,
20 field memory 55, limiter 56 and output terminal 57. The operation of the cyclic type noise reduction circuit has been described in connection with the related art.

Light from an object received by the zoom lens 11
25 is adjusted in amount by the diaphragm 12 and focussed on the surface of the image pickup device. After the light is converted into an electric signal by the image

pickup device 13, the electric signal is supplied to the sample/hold AGC unit 14, A/D converted by the A/D converter unit 15, and input to the video signal processing unit 16.

5 The video signal processing unit 16 performs aperture correction, gamma correction, white balance correction and the like for each brightness and color component of an input signal, to thereby generate a video signal which is output to the electronic zoom
10 unit 17. The electronic zoom unit 17 performs image cut and paste, magnification, and interpolation by using the field memory so that an output image has a magnification factor relative to an input image, the magnification factor being determined by a control
15 signal supplied from the system control unit 21.

The noise reduction unit 18 reduces noises in the video signal in response to a control signal supplied from the system control unit 21. The noise reduced video signal is output to a recorder or the like connected to the noise reduction unit 18.
20

25 The system control unit 21 controls each component of the image sensing apparatus. As the wide key 23 or telephoto key 24 of the zoom operation key unit 22 is depressed, the system control unit 21 also controls the lens drive unit 20 or electronic zoom unit 17 to move the zoom lens in the wide or telephoto direction.

The system control unit 21 judges, from a lens

position detection signal supplied from the lens position detection unit 19, at which position (zoom magnification factor) including the telephoto end (furthest telephoto end) and wide end (widest angle end), the zoom lens is. A function of magnifying an image picked up with a lens optical system is called an optical zoom, whereas a function of vertically and horizontally magnifying an image by an electronic signal process without using the lens optical system is called an electronic zoom.

The system control unit 21 generally performs the optical zoom by driving the zoom lens 11 in the range of a magnification factor which can be set with the optical zoom. After the zoom lens 11 arrives at the telephoto end, the image is electronically magnified by the electronic zoom under the control of the electronic zoom unit 17. In this embodiment, the maximum magnification factor of the optical zoom is set to 12 times and the maximum magnification factor of the electronic zoom is set to 4 times, so that the zoom operation with the high magnification factor of 48 times is possible.

The system control unit 21 outputs a noise reduction control signal to the noise reduction unit 18, the control signal being set differently in case of that the optical and electronic zooms are stopped and in a case of that the zooms are operated, so that the

amount of noise reduction can be changed. The noise reduction control signal corresponds to the cyclic coefficient K.

This control signal is also changed with the
5 brightness of an object. The S/N of a video signal lowers as the brightness of an object becomes dark. In order to compensate for this, the control signal is changed to make the noise reduction amount larger.

In order to maintain the level of a video signal
10 at a predetermined value even if the amount of input light from an object changes, the system control unit 21 controls the diaphragm 12, sample/hold AGC unit 14, electronic shutter (not shown in Fig. 1) and the like by judging the brightness of the object collectively
15 from a diaphragm value, an AGC gain, an electronic shutter speed and the like (hereinafter called exposure control data) used for exposure control.

Next, the optical zoom, electronic zoom and noise reduction controls by the system control unit 21 will
20 be described. Figs. 4 and 5 are flow charts illustrating the noise reduction control process. The program for this process is stored in ROM 32 of the system control unit 21 and executed by CPU 31.

The system control unit 21 judges whether the
25 telephoto key 24 is depressed (Step S201). If depressed, it is checked whether the position of the zoom lens is at the telephoto end (optical zoom

magnification factor of 12 times) (Step S203). If the position of the zoom lens 11 is the telephoto end, the zoom lens 11 is fixed to the telephoto end (Step S204).

It is then checked whether the electronic zoom
5 magnification factor of the electronic zoom unit 17 is the maximum of 4 times. If 4 times, the electronic zoom magnification factor is fixed to 4 times (Step S206). If not the maximum of 4 times, the electronic zoom unit 17 is controlled to increase the
10 magnification factor to a predetermined value (Step S207). In this embodiment, although the maximum magnification factor of the optical zoom is set to 12 times and that of the electronic zoom is set to 4 times, other magnification factors may also be set.

15 If the position of the zoom lens 11 is not the telephoto end at Step S203, the lens drive unit 20 is controlled to move the zoom lens 11 in the telephoto direction and increase the magnification factor to a predetermined value (Step S208). The magnification factor of the electronic zoom is fixed to an equal
20 magnification (Step S209).

If the telephoto key 201 is not depressed at Step S201, it is checked whether the wide key 23 is depressed (Step S202). If depressed, it is checked
25 whether the electronic zoom magnification factor of the electronic zoom unit 17 is the minimum of the equal magnification (Step S212).

If the electronic magnification factor is the minimum of the equal magnification, the electronic zoom unit 17 is controlled to fix the electronic zoom magnification factor to the equal magnification. It is
5 then checked whether the position of the zoom lens 11 is the wide end (optical zoom magnification factor of equal magnification) (Step S214). If the position is the wide end, the zoom lens 11 is fixed to the wide end (Step S215).

10 If the position of the zoom lens 11 is not the wide end, the lens drive unit 20 is controlled to move the zoom lens 11 in the wide direction and reduce the magnification factor to a predetermined value (Step S216).

15 If the electronic zoom magnification factor is not the equal magnification at Step S212, the electronic zoom unit 17 is controlled to reduce the magnification factor of the electronic zoom to a predetermined value (Step S217). The zoom lens 11 is fixed to the
20 telephoto end (Step S218).

If the wide key 23 is not depressed at Step S202, the electronic zoom unit 17 is controlled to fix the electronic zoom magnification factor without being changed (Step S210). In order to fix the electronic zoom magnification factor of the zoom lens 11, the lens
25 drive unit 20 is controlled to stop the zoom lens 11 (Step S211).

Under the conditions that the electronic zoom unit 17 and zoom lens 11 are stopped, the noise reduction unit 18 is controlled to set the noise reduction control mode to a zoom stop mode (Step S219).

5 Under the conditions that either the electronic zoom unit 17 or the zoom lens 11 is operated, the noise reduction unit 18 is controlled to set the noise reduction control mode to a zoom operation mode (Step S220). Thereafter, the system control unit 21
10 temporarily terminates the process, and after it controls each component of the image sensing apparatus, it again repeats the process from Step S201 to Step S220.

As described above, according to this embodiment,
15 it is judged whether the zoom variable magnification operation is being executed. In accordance with this judgement, the cyclic coefficient of the noise reduction is changed. This method is more effective than the case wherein a motion vector of an image under
20 the variable magnification operation is detected and in accordance with the detection result, the noise reduction is changed. The reason for this is as follows. Since the mechanism for detecting a motion vector of an image is a feedback loop, there is a delay
25 in changing the noise reduction. Also, the motion vector of an image under the variable magnification operation diverges so that the motion vector of the

whole image converges to zero. A proper detection is therefore impossible.

Fig. 6 is a graph showing the relation between the cyclic coefficient K and the brightness of an object in the zoom stop mode and in the zoom operation mode.

5 Steps S219 and S220 are executed in accordance with the graph shown in Fig. 6. The ordinate represents the cyclic coefficient K of the noise reduction. As the cyclic coefficient K changes from "0" to nearer to "1",

10 the noise reduction amount becomes larger and the latent image becomes more conspicuous. As shown in

Fig. 6, the cyclic coefficient K of the noise reduction is set smaller during the zoom operation (zoom operation mode) than during the zoom stop mode to lower 15 the noise reduction amount. The latent image

phenomenon can therefore be suppressed. The abscissa represents the brightness of an object which is judged from the exposure control data. The brightness of an 20 object is divided into areas A, B, C and D from the brighter side in accordance with a predetermined reference value.

In the zoom stop mode, the cyclic coefficient K of the noise reduction is "31/32" in the brightest area A of an object. As the brightness of the object changes 25 to the area B, the cyclic coefficient is changed to "63/64". As the area changes to the areas C and D, the value is changed to "127/128" and "255/256"

respectively. Similarly, as the area changes from the area D to the area A, the cyclic coefficient is changed from the value "255/256" to the value "31/32".

In the zoom operation mode, the cyclic coefficient K of the noise reduction is "3/4" in the area A. As the area changes to the areas B, C and D, the coefficient changes to the values "7/8", "15/16" and "31/32" respectively, similar to the zoom stop mode.

As above, the cyclic coefficient K of the noise reduction takes the value on a zoom stop mode control line or on a zoom operation mode control line shown in Fig. 6, in accordance with a change in the brightness of an object. The value on the zoom operation mode control line takes a value nearer to "0" than the value on the zoom stop mode control line, at each brightness of an object.

The value of the cyclic coefficient K of the noise reduction may take any value so long as it makes the noise reduction amount of a picked-up image smaller in the zoom operation mode than in the zoom stop mode.

The value of the cyclic coefficient K used in this embodiment is not therefore limited only thereto. So long as the value can change the noise reduction amount, the control value other than the cyclic coefficient may also be used.

In this embodiment, the cyclic coefficient K of the noise reduction can take the value only on the zoom

stop mode control line and the zoom operation mode control line shown in Fig. 6, in the zoom stop mode, the zoom operation mode, a transfer from the zoom stop mode to zoom operation mode and a transfer from the 5 zoom operation mode to zoom stop mode. If there is a large difference in the noise reduction amount between the noise reduction control value in the zoom stop mode and the noise reduction control value in the zoom operation mode, intermediate modes Step 1 and Step 2 10 may be provided between the zoom stop and operation modes as shown in Fig. 7 to use the cyclic coefficients K at Steps 1 and 2 when the mode is transferred. In this manner, it is possible to suppress the influence, upon images, of switching between the noise reduction 15 control value during the mode transfer. Fig. 7 is a graph showing the relation between the object brightness and the cyclic coefficient K in the zoom stop and operation modes and at Steps 1 and 2.

In the optical zoom or electronic zoom operation 20 of the embodiment, a change in the magnification factor per unit time may be increased or decreased to stepwise change the zoom speed in accordance with the depression force of the wide key or telephoto key. For example, if the zoom speed is increased more as the key is 25 depressed more strongly, the control value K of the noise reduction is gradually lowered in proportion to the zoom speed to thereby suppress the latent image

phenomenon. For example, if the zoom speed has three levels, low speed, middle speed and high speed, Step 1 shown in Fig. 7 is used at the low speed, Step 2 is used at the middle speed, and the zoom operation mode control line is used at the high speed to thereby lower the value K in proportion to the zoom speed. In this manner, influence of the zoom speed upon images can be suppressed by switching the noise reduction control value.

Also in this embodiment, the zoom lens 11 for optically changing the size of a picked-up image and the electronic zoom unit 17 for changing the size of a picked-up image through electronic signal processing are used in combination. The embodiment is applicable also to the case wherein either the zoom lens 11 or the electronic zoom unit 17 is used.

In this embodiment, as shown in Fig. 1, a video signal is processed by the electronic zoom unit 17 for the electronic zoom of an image, and thereafter, the noise reduction unit 18 performs a noise reduction operation. In another embodiment of the invention, as shown in Fig. 9, an electronic zoom unit 17 may be provided at the succeeding stage of a noise reduction unit 18.

The flow charts illustrating the operation of an image sensing apparatus having the structure shown in Fig. 9 are shown in Figs. 10 and 11. In the flow

charts shown in Figs. 10 and 11, Steps having reference numerals identical to those shown in Figs. 4 and 5 execute the operations similar to those described with reference to Figs. 4 and 5, and the descriptions
5 thereof are omitted.

At Step S207 shown in Fig. 10, if an image magnification operation is being executed by the electronic zoom, the flow advances to Step S219 whereat the noise reduction is switched to the zoom stop mode
10 to increase the noise reduction cyclic coefficient K similar to the case of that the zoom operation is stopped.

At Step S217 shown in Fig. 11, if an image reduction operation is being executed by the electronic zoom, the zoom lens is stopped at the telephoto end
15 (Step S218) to thereafter follow Step S219 whereat the noise reduction is switched to the zoom stop mode to increase the noise reduction cyclic coefficient K similar to the case of that the zoom operation is
20 stopped.

In this embodiment, while the electronic zoom is executed, even if the cyclic coefficient K of the noise reduction is made large similar to the coefficient K of the zoom stop mode, the latent image phenomenon will
25 not occur while the electronic zoom is executed and noises can be reduced, because the electronic zoom is executed after the noise reduction of a video signal.

The invention is also applicable to a system constituted of a plurality of apparatus or to a single apparatus. It is obvious that the object of the invention can be achieved by supplying a system or apparatus with a software program. In this case, the system or apparatus reads the program stored in a storage medium to realize the functions and effects of the invention.

Fig. 8 is a memory map of ROM 32 as such a storage medium. ROM 32 stores a noise reduction control program module realizing the process of the flow charts shown in Figs. 4 and 5, the table values of the cyclic coefficient K shown in the graph of Fig. 6, and the table values of the cyclic coefficient K shown in the graph of Fig. 7.

The storage medium storing the program module is not limited only to ROM, but other media may be used such as a floppy disk, a hard disk, an optical disk, a magneto-optical disk, a CD-ROM, a CD-R, a DVD, a magnetic tape, and a nonvolatile memory card.

The scope of the invention also contains the case wherein the functions of each embodiment can be realized by writing the program codes read from the storage medium into a memory of a function expansion board inserted into a computer or of a function expansion unit connected to the computer, and thereafter by executing a portion or the whole of

actual processes by a CPU of the function expansion board or function expansion unit.

As described so far, according to the image sensing apparatus of the embodiments, the control value of the noise reduction unit is set to a value providing a smaller noise reduction amount in the variable magnification operation mode than in the variable magnification stop mode. Therefore, irrespective of the telephoto or wide zoom operation direction, the noise reduction amount is set smaller in the zoom operation mode than in the zoom stop mode so that the latent image phenomenon to be caused by a change in the size of an object image during the zoom operation mode can be suppressed.

According to the image sensing apparatus of the embodiments, the control value of the noise reduction is changed with a control value for the exposure adjustment which maintains the level of a generated video signal constant irrespective of the amount of light from an object. It is therefore possible to increase the noise reduction amount so as to compensate for the S/N of a video signal to be degraded by the dark brightness of an object. The invention is therefore applicable to provide larger noise reduction amount of an object at a low brightness more than that of an object at a sufficient brightness.

Many widely different embodiments of the present

invention may be constructed without departing from the spirit and scope of the present invention. It should be understood that the present invention is not limited to the specific embodiments described in the specification, except as defined in the appended claims.

WHAT IS CLAIMED IS:

1. An image sensing apparatus comprising:
noise reduction means for reducing noises of a
sensed image by utilizing images having correlation in
5 time;
zoom control means for controlling a zoom
magnification factor of the image sensing apparatus;
judging means for judging whether said zoom
control means is executing a zoom operation; and
10 setting means for setting a control value for said
noise reduction means in accordance with a judgement
result by said judging means.
2. The apparatus according to claim 1, wherein
15 said setting means sets the control value providing a
lower noise reduction amount than an amount to be used
when the zoom operation is stopped, if said judging
means judges that the zoom operation is executed.
- 20 3. The apparatus according to claim 1, wherein
said setting means sets the control value for said
noise reduction means in accordance with a
magnification factor per unit time used by said zoom
control means.
- 25 4. The apparatus according to claim 1, further
comprising exposure control means for controlling an

exposure of the picked-up image, wherein said setting means changes the control value for said noise reduction means in accordance with a control value for said exposure control means.

5

5. The apparatus according to claim 1, wherein said setting means stepwise changes the control value for said noise reduction means when the zoom operation transfers from an execution state to a stop state.

10

6. The apparatus according to claim 1, wherein said setting means stepwise changes the control value for said noise reduction means when the zoom operation transfers from a stop state to an execution state.

15

7. The apparatus according to claim 1, further comprising optical zoom means for optically zooming an image of an object and electronic zoom means for electronically processing the image of the object, wherein said zoom control means controls said optical zoom means for optically zooming the image of the object and said electronic zoom means for electronically processing the image of the object.

20

25 8. The apparatus according to claim 7, wherein said electronic zoom means executes the zoom operation for an image whose noises were reduced by said noise

reduction means, and said setting means sets the control value providing a lower noise reduction amount than an amount to be used when said electronic zoom means executes the zoom operation, if it is judged that
5 said optical zoom means executes the zoom operation.

9. An image sensing method comprising the steps of:

reducing noises of a sensed image by utilizing
10 images having correlation in time;
controlling a zoom magnification factor of the image sensing apparatus;
judging whether said zoom control step is executing a zoom operation; and
15 setting a control value for said noise reduction step in accordance with a judgement result at said judging step.

10. The method according to claim 9, wherein said
20 setting step sets the control value providing a lower noise reduction amount than an amount to be used when the zoom operation is stopped, if said judging step judges that the zoom operation is executed.

25 11. The method according to claim 9, wherein said setting step sets the control value for said noise reduction step in accordance with a magnification

factor per unit time used at said zoom control step.

12. The method according to claim 9, further comprising a step of controlling an exposure of the
5 picked-up image, wherein said setting step changes the control value for said noise reduction step in accordance with a control value for said exposure control step.

10 13. The method according to claim 9, wherein said setting step stepwise changes the control value for said noise reduction step when the zoom operation transfers from an execution state to a stop state.

15 14. The method according to claim 9, wherein said setting step stepwise changes the control value for said noise reduction step when the zoom operation transfers from a stop state to an execution state.

20 15. The method according to claim 9, further comprising a step of optically zooming an image of an object and a step of electronically processing the image of the object, wherein said zoom control step controls said optical zoom step of optically zooming
25 the image of the object and said electronic zoom step of electronically processing the image of the object.

16. The method according to claim 15, wherein
said electronic zoom step executes the zoom operation
for an image whose noises were reduced at said noise
reduction step, and said setting step sets the control
5 value providing a lower noise reduction amount than an
amount to be used when said electronic zoom step
executes the zoom operation, if it is judged that said
optical zoom step executes the zoom operation.

10 17. A storage medium storing a program for
executing an image sensing method, said method
comprising the steps of:

reducing noises of a sensed image by utilizing
images having correlation in time;

15 controlling a zoom magnification factor of the
image sensing apparatus;

judging whether said zoom control step is
executing a zoom operation; and

20 setting a control value for said noise reduction
step in accordance with a judgement result at said
judging step.

ABSTRACT OF THE DISCLOSURE

An image sensing apparatus is provided which can sense an image of an object always in good conditions by realizing an optimum noise reduction process even under various photographing conditions and even with various functions of the apparatus. A system control unit of the apparatus controls a noise reduction unit by setting the noise reduction control mode to a zoom stop mode under the conditions that an electronic zoom unit and a zoom lens are stopped, and controls the noise reduction unit by setting the noise reduction control mode to a zoom operation mode under that the conditions that either the electronic zoom unit or the zoom lens is operated.

FIG. 1

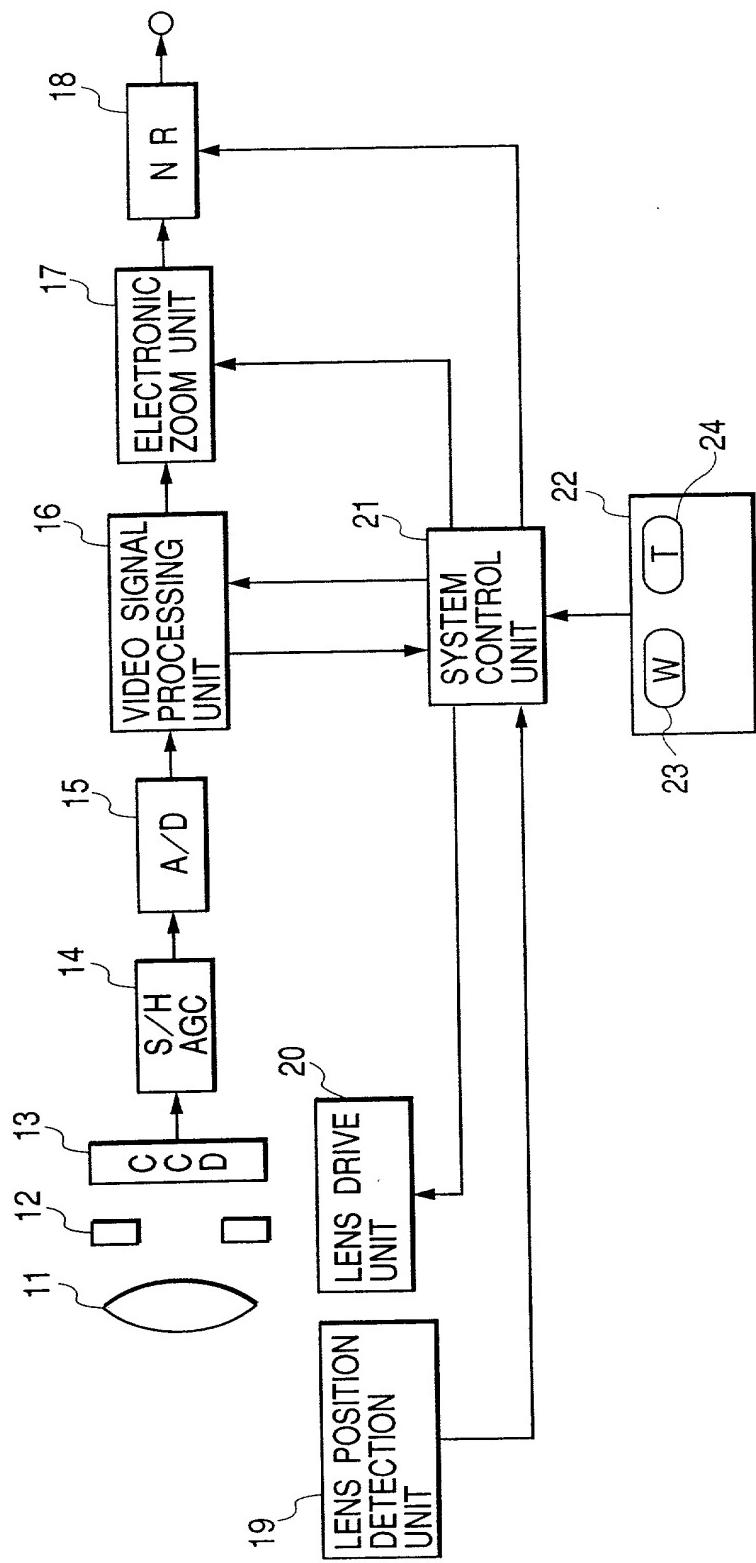


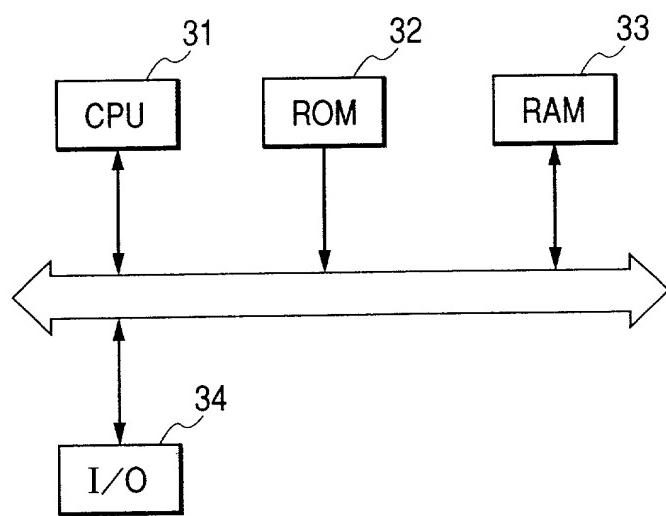
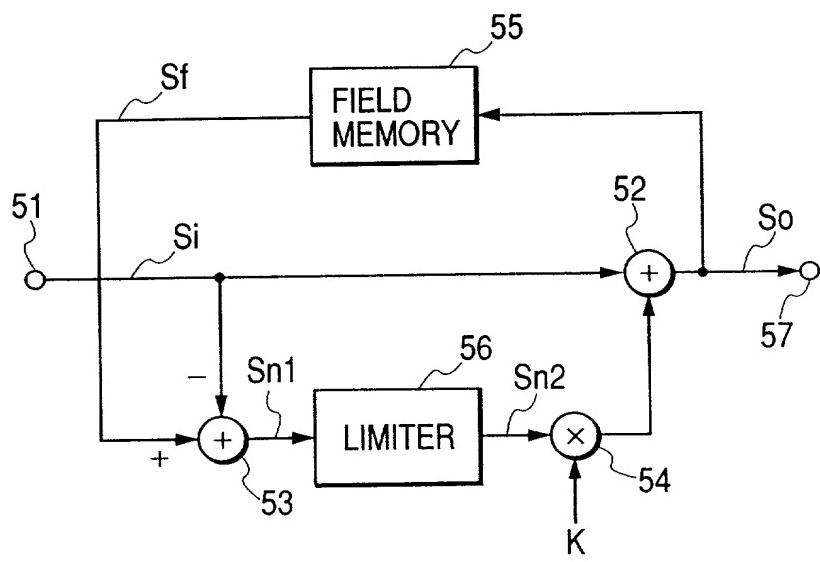
FIG. 2***FIG. 3***

FIG. 4

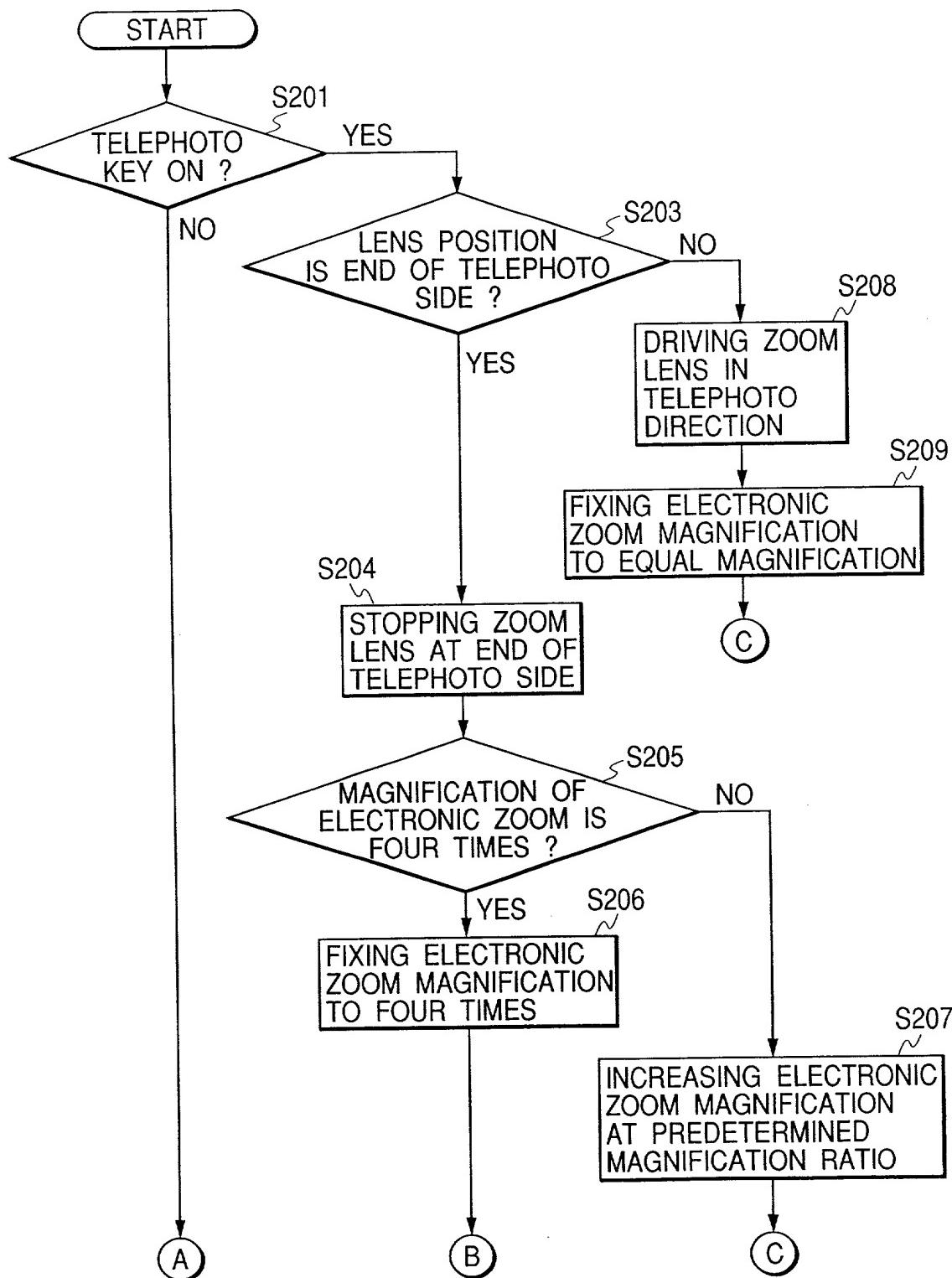


FIG. 5

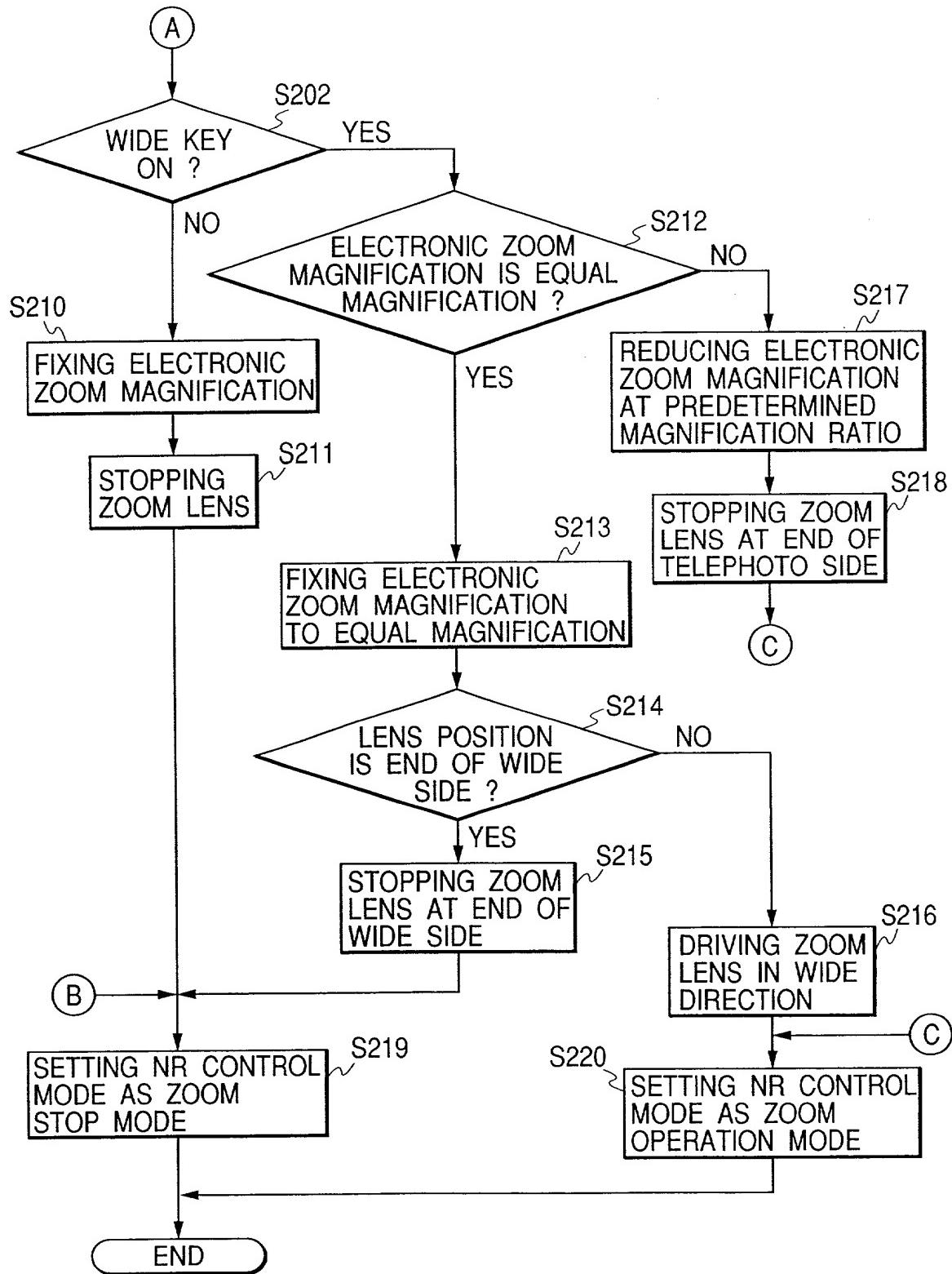


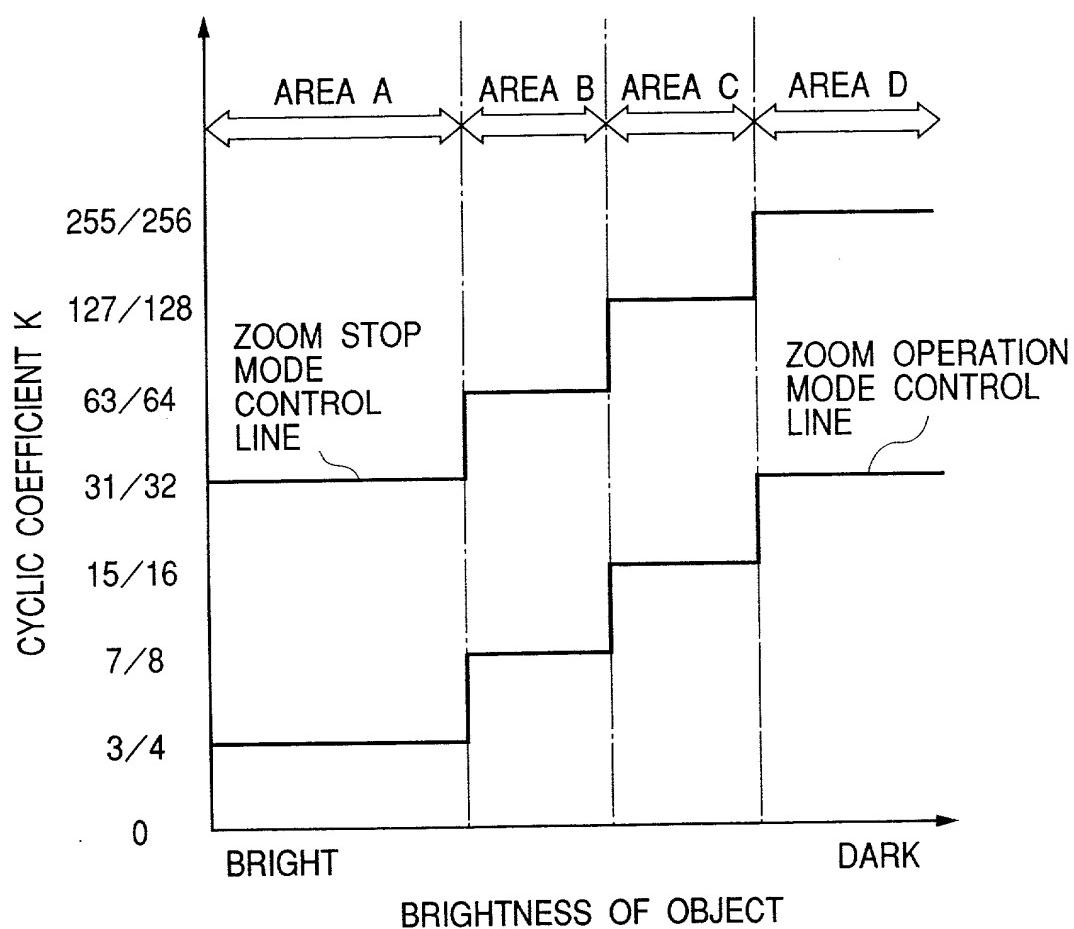
FIG. 6

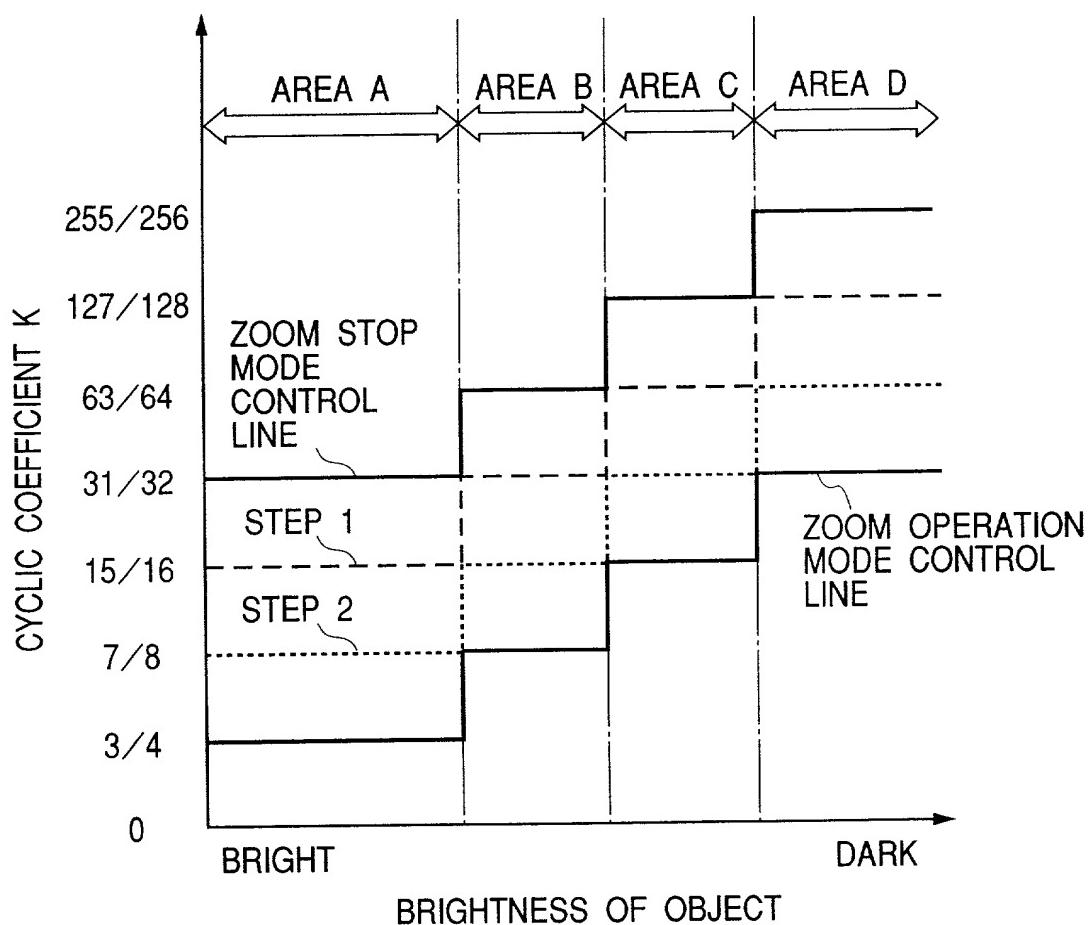
FIG. 7

FIG. 8

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DIRECTORY INFORMATION	
PROGRAM MODULE OF NOISE REDUCTION CONTROL PROCESSING SHOWN IN FIGS. 4 AND 5	
TABLE VALUE OF CYCLIC COEFFICIENT SHOWN BY GRAPH IN FIG. 6	
TABLE VALUE OF CYCLIC COEFFICIENT SHOWN BY GRAPH IN FIG. 7	
⋮	

FIG. 9

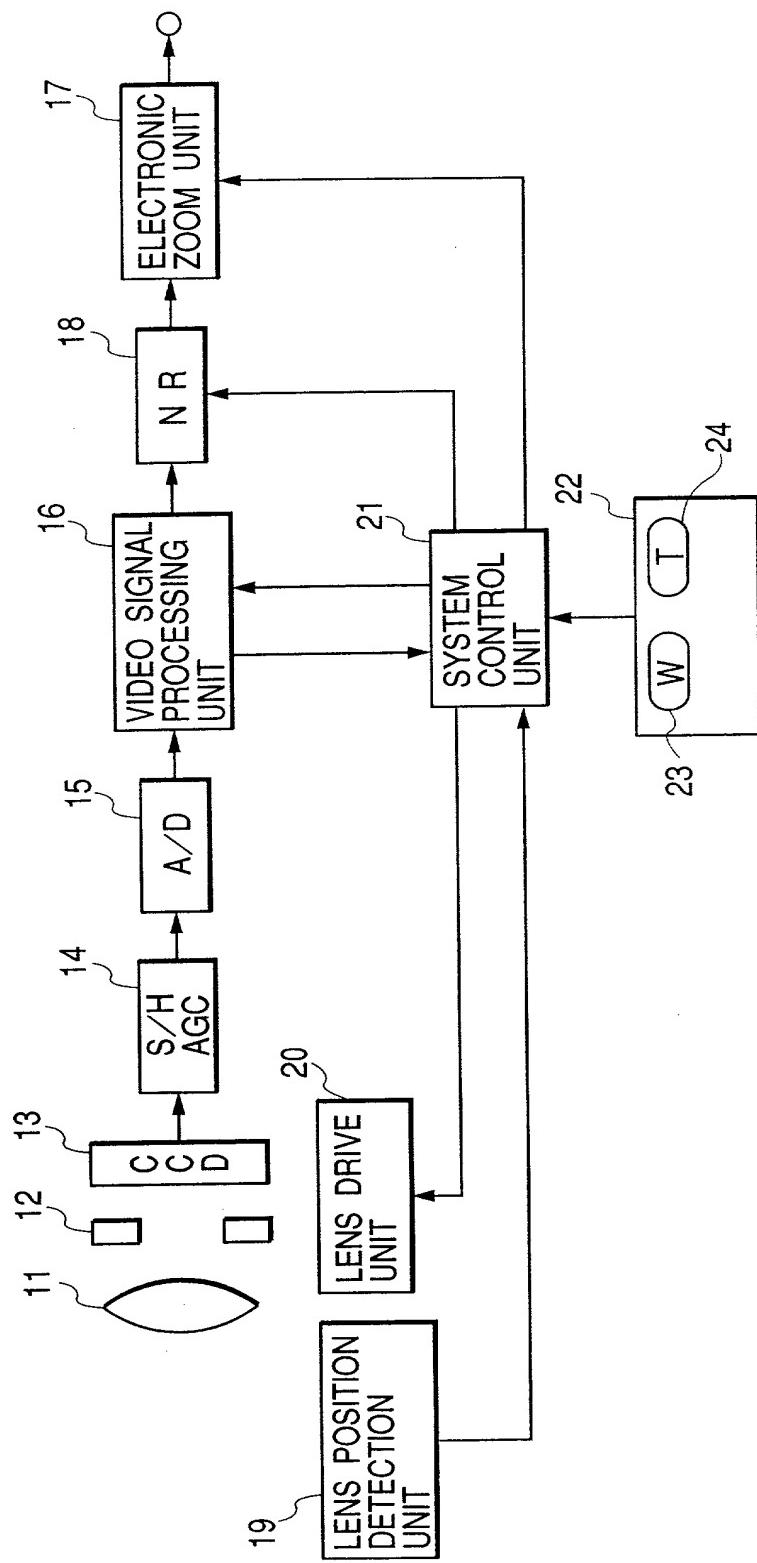


FIG. 10

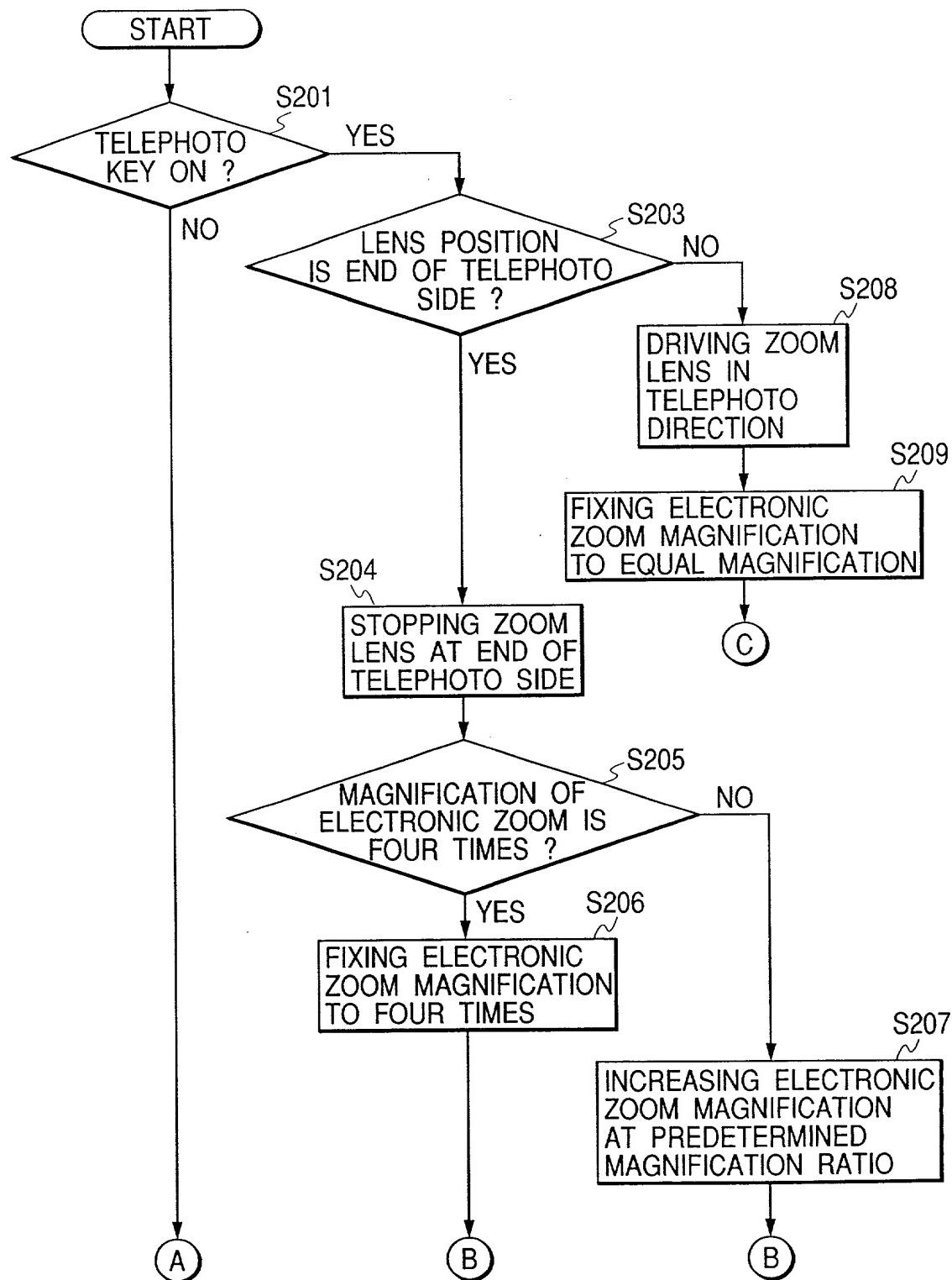
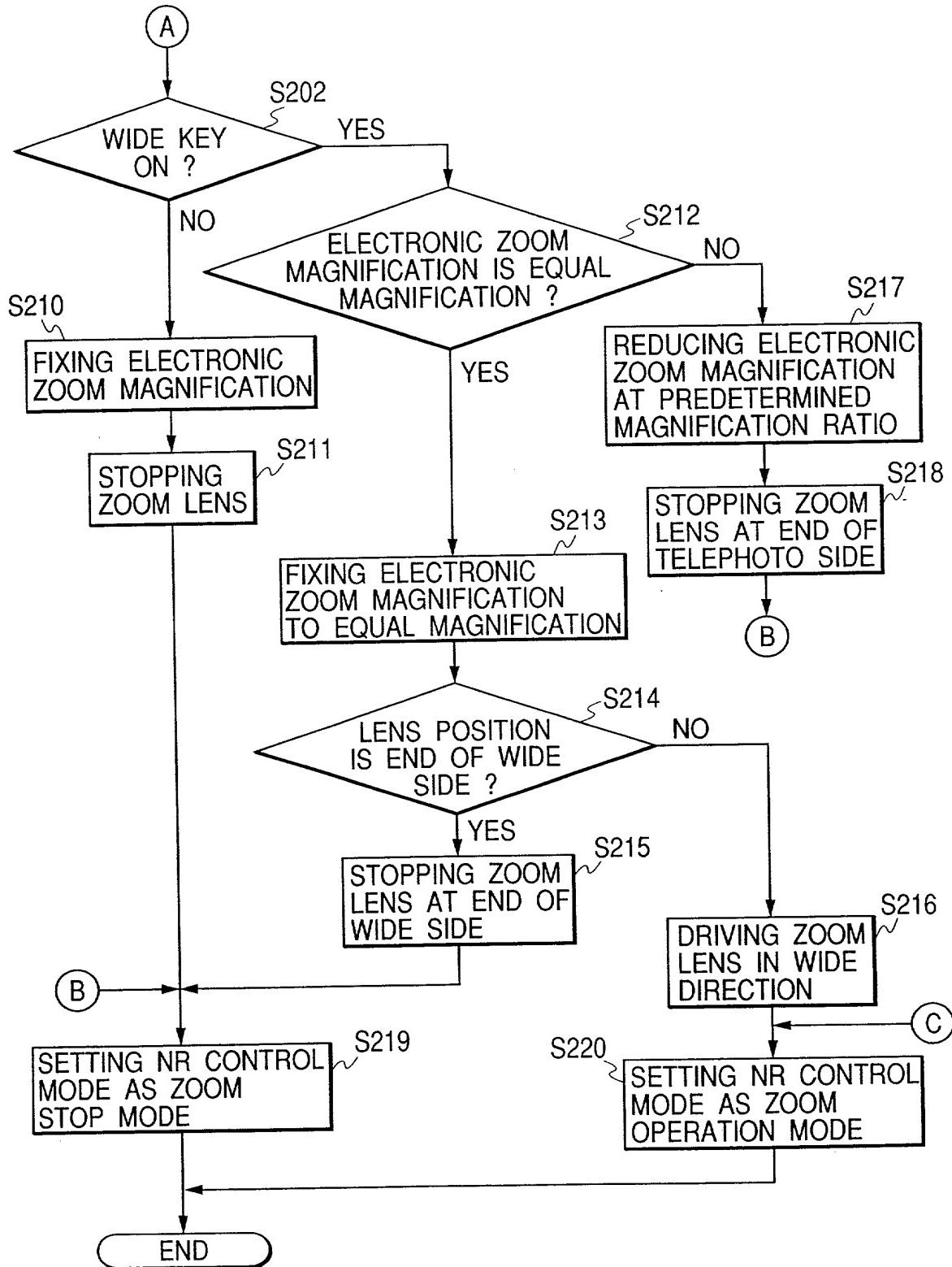


FIG. 11



**COMBINED DECLARATION AND POWER OF ATTORNEY
FOR PATENT APPLICATION**
(Page 1)

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled **IMAGE SENSING APPARATUS**

the specification of which is attached hereto was filed on _____ as United States Application No. or PCT International Application No. _____ and was amended on _____ (if applicable).

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR §1.56.

I hereby claim foreign priority benefits under 35 U.S.C. §119(a)-(d) or §365(b), of any foreign application(s) for patent or inventor's certificate, or § 365(a) of any PCT international application which designates at least one country other than the United States, listed below and have also identified below any foreign application for patent or inventor's certificate, or PCT international application having a filing date before that of the application on which priority is claimed:

Country	Application No.	Filed (Day/Mo./Yr.)	(Yes/No)
			Priority Claimed
JAPAN	11-013945	22/JANUARY/1999	Yes

I hereby claim the benefit under 35 U.S.C. § 120 of any United States application(s), or § 365(c) of any PCT international application designating the United States, listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States or PCT international application in the manner provided by the first paragraph of 35 U.S.C. § 112, I acknowledge the duty to disclose information which is material to patentability as defined in 37 C.F.R. § 1.56 which became available between the filing date of the prior application and the national or PCT international filing date of this application.

Application No.	Filed (Day/Mo./Yr.)	Status (Patented, Pending, Abandoned)

I hereby appoint the practitioners associated with the firm and Customer Number provided below to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith, and direct that all correspondence be addressed to the address associated with that Customer Number:

FITZPATRICK, CELLA, HARPER & SCINTO
Customer Number: 05514

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Full Name of Sole or First Inventor **MASAHIKO KIKUZAWA**

Inventor's signature _____

Date _____

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3-chome, Ohta-ku, Tokyo, Japan

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